

1 4. (Previously Presented) The system of claim 1, wherein said mobile robot has a
2 microphone, and said first and second remote stations each have a speaker that receive a sound
3 from said microphone.

1 5. (Previously Presented) The system of claim 1, wherein said mobile robot
2 includes a monitor and a speaker, and said first remote station includes a camera and a
3 microphone.

1 6. (Previously Presented) The system of claim 1, wherein said mobile robot
2 includes a platform that provides three degrees of freedom.

1 7. (Previously Presented) The system of claim 1, further comprising a base station
2 wirelessly coupled to said mobile robot.

1 8. (Currently Amended) A mobile robot system, comprising:
2 a mobile robot that can move across a surface, has a first camera that capture a video
3 image;
4 first remote station means for controlling movement of said mobile robot and displaying
5 the video image, said first remote station means being separate from said mobile robot; and,
6 second remote station means for displaying the video image, said second remote station
7 means being separate from said mobile robot.

1 9. (Previously Presented) The system of claim 8, wherein said first remote station
2 means receives the video image from said mobile robot, and retransmits the video image to said
3 second remote station means.

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1 10. (Previously Presented) The system of claim 8, wherein said mobile robot
2 broadcast the video image to said first and second remote stations means.

1 11. (Previously Presented) The system of claim 8, wherein said mobile robot has a
2 microphone, and said first and second remote station means each emit a sound provided by said
3 microphone.

1 12. (Previously Presented) The system of claim 8, wherein said mobile robot
2 includes a monitor and a speaker, and said first remote station means includes a camera and a
3 microphone.

1 13. (Previously Presented) The system of claim 8, wherein said mobile robot
2 includes a platform that provides three degrees of freedom.

1 14. (Previously Presented) The system of claim 8, further comprising a base station
2 wirelessly coupled to said mobile robot.

1 15. (Currently Amended) A method for operating a mobile robot, comprising:
2 controlling movement of a mobile robot across a surface through a first remote station
3 that is separate from the mobile robot, the mobile robot having a camera that captures a video
4 image;
5 displaying the video image at the first remote station and a second remote station that is
6 separate from the mobile robot.

1 16. (Original) The method of claim 15, wherein the first remote station receives and
2 retransmits the video image to the second remote station.

1 17. (Previously Presented) The method of claim 15, wherein the mobile robot
2 broadcast the video image to the first and second remote stations.

1 18. (Previously Presented) The method of claim 15, further comprising generating a
2 sound at the first and second remote stations that is provided by the mobile robot.

1 19. (Currently Amended) A mobile robot system, comprising:
2 a broadband network;
3 a mobile robot that can move across a surface, said mobile robot being coupled to said
4 broadband network and has a camera that captures a video image;
5 a first remote station that is coupled to said broadband network, said first remote station
6 has a first monitor and an input device that receives input to cause movement of said mobile
7 robot, said first monitor displays the video image from said camera, said first remote station
8 being separate from said mobile robot; and,
9 a second remote station that is coupled to said broadband network and has a second
10 monitor that also displays the video image, said second remote station being separate from said
11 mobile station.

1 20. (Previously Presented) The system of claim 19, wherein said first remote station
2 receives the video image from said mobile robot through said broadband network, and
3 retransmits the video image to said second remote station.

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1 21. (Previously Presented) The system of claim 19, wherein said mobile robot
2 broadcast the video image to said first and second remote stations through said broadband
3 network.

1 22. (Previously Presented) The system of claim 19, wherein said mobile robot has a
2 microphone, and said first and second remote stations each have a speaker that receive a sound
3 from said microphone transmitted through said broadband network.

1 23. (Previously Presented) The system of claim 19, wherein said mobile robot
2 includes a monitor and a speaker, and said first remote station includes a camera and a
3 microphone.

1 24. (Previously Presented) The system of claim 19, wherein said mobile robot
2 includes a platform that provides three degrees of freedom.

1 25. (Previously Presented) The system of claim 19, further comprising a base station
2 that is coupled to said broadband network and wirelessly coupled to said mobile robot.

1 26. (Currently Amended) A mobile robot system, comprising:
2 a broadband network;
3 a mobile robot that is coupled to said broadband network and has a camera that captures a
4 video image that is transmitted through said broadband network;
5 first remote station means for controlling movement of said mobile robot and displaying
6 the video image transmitted through said broadband network, said first remote station means
7 being separate from said mobile robot; and,

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8 second remote station means for displaying the video image, said second remote station
9 means being separate from said mobile robot.

1 27. (Previously Presented) The system of claim 26, wherein said first remote station
2 means receives the video image from said mobile robot, and retransmits the video image to said
3 second remote station.

1 28. (Previously Presented) The system of claim 26, wherein said mobile robot
2 broadcast the video image to said first and second remote stations means.

1 29. (Previously Presented) The system of claim 26, wherein said mobile robot has a
2 microphone, and said first and second remote station means each emit a sound provided by said
3 microphone transmitted through said broadband network.

1 30. (Previously Presented) The system of claim 26, wherein said mobile robot
2 includes a monitor and a speaker, and said first remote station means includes a camera and a
3 microphone.

1 31. (Previously Presented) The system of claim 26, wherein said mobile robot
2 includes a platform that provides three degrees of freedom.

1 32. (Previously Presented) The system of claim 26, further comprising a base station
2 that is coupled to said broadband network and is wirelessly coupled to said mobile robot.

1 33. (Currently Amended) A method for operating a mobile robot, comprising:
2 controlling movement of a mobile robot across a surface through a first remote station
3 and a broadband network, the mobile robot having a camera that captures a video image, the first
4 remote station being separate from the mobile robot;
5 transmitting the video image through the broadband network; and,
6 displaying the video image at the first remote station and a second remote station that is
7 separate from the mobile robot.

1 34. (Original) The method of claim 33, wherein the first remote station receives and
2 retransmits the video image to the second remote station.

1 35. (Previously Presented) The method of claim 33, wherein the mobile robot
2 broadcast the video image to the first and second remote stations.

1 36. (Previously Presented) The method of claim 33, further comprising generating a
2 sound at the first and second remote stations that is provided by the mobile robot.

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